

GLOBAL FOCUS ON KNOWLEDGE
“CREATING MATHEMATICS”
—THE CHALLENGE OF MATHEMATICIANS—

2009 winter semester

Lecture 1 “How Mathematics Was Created”

2009/10/08 Kazuo Murota $\oplus$ Kazuo Okamoto

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WHAT IS MATHEMATICS?

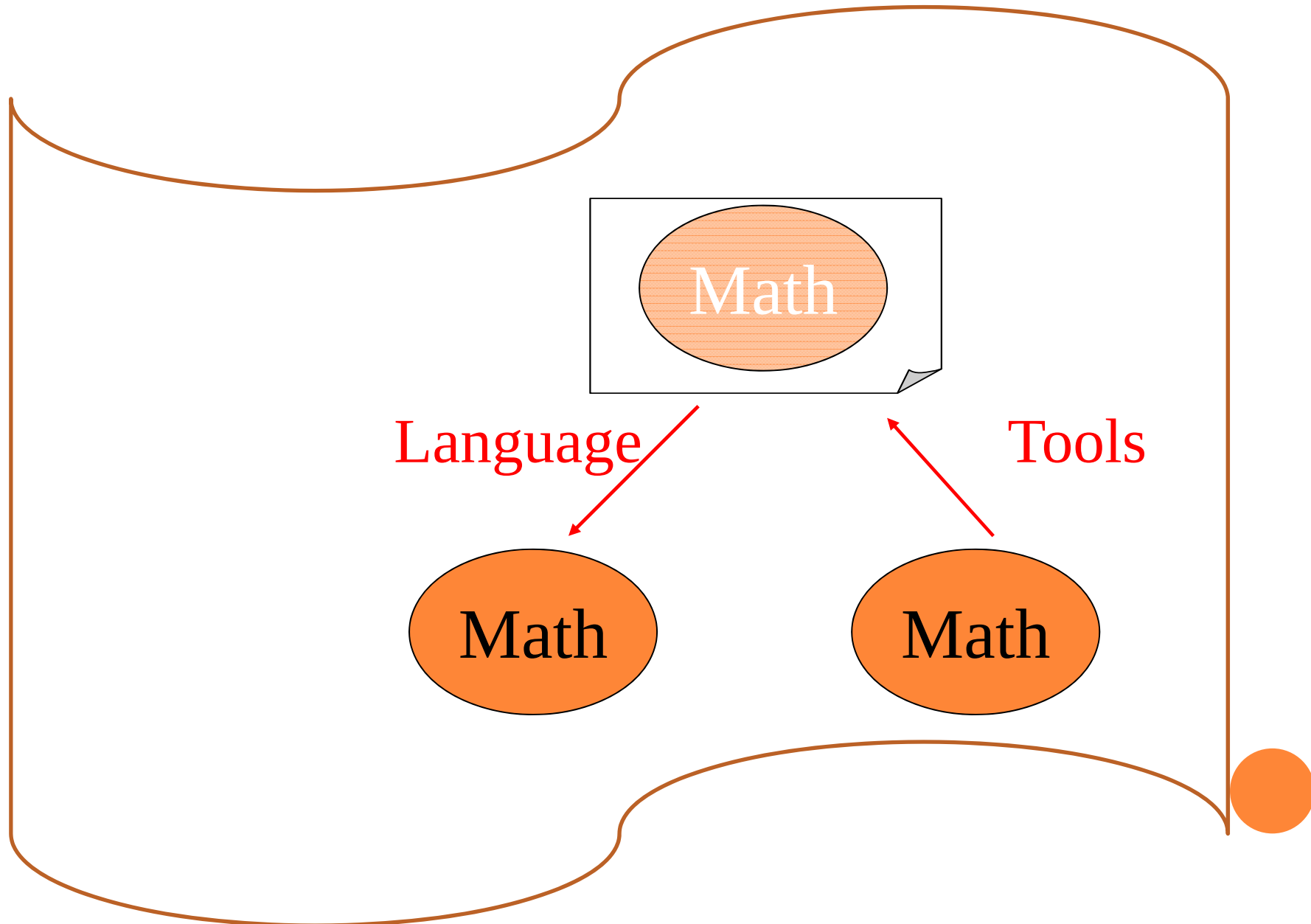
- What does it deal with?
- Where has it been brought up?
- What does it originate from?

THREE FORMS OF MATHEMATICS

- Sugaku (math), Sugaku (enjoy math), Sugaku (suffer from math)
- mathematics as a **language**
- mathematics as a **tool**
- mathematics as an **object**



“Create Mathematics”?





“Mathematics is the language with which God has written the universe”

Galileo Galilei
1564-1642



INCENTIVES TO CREATE MATHEMATICS

When we want to

- discover something,
 - solve some problem,
 - or simply use math
-
- Incentives to **create new mathematics** lie in nature, society, or math itself
 - “Necessity is the mother of invention”, but **playful mind** is also important
 - **Change the point of view**



$$0 + 4 =$$

$$3 + 4 =$$

$$3 \times 2 + 4 =$$

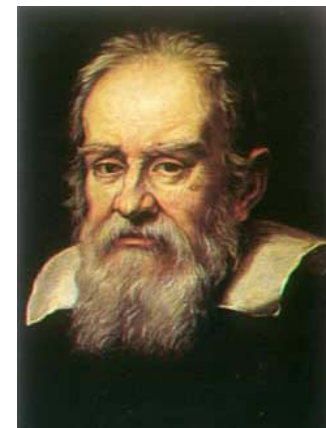
$$3 \times 2^2 + 4 =$$

$$3 \times 2^3 + 4 =$$

$$3 \times 2^4 + 4 =$$

$$3 \times 2^5 + 4 =$$

Sequence
calculation



$$0 + 4 = 4,$$

$$3 + 4 = 7,$$

$$3 \times 2 + 4 = 10$$

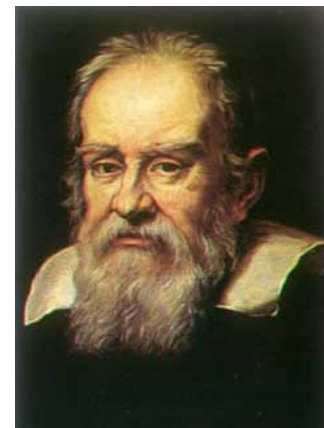
$$3 \times 2^2 + 4 = 16,$$

$$3 \times 2^3 + 4 = 28,$$

$$3 \times 2^4 + 4 = 52,$$

$$3 \times 2^5 + 4 = 100$$

Good
work



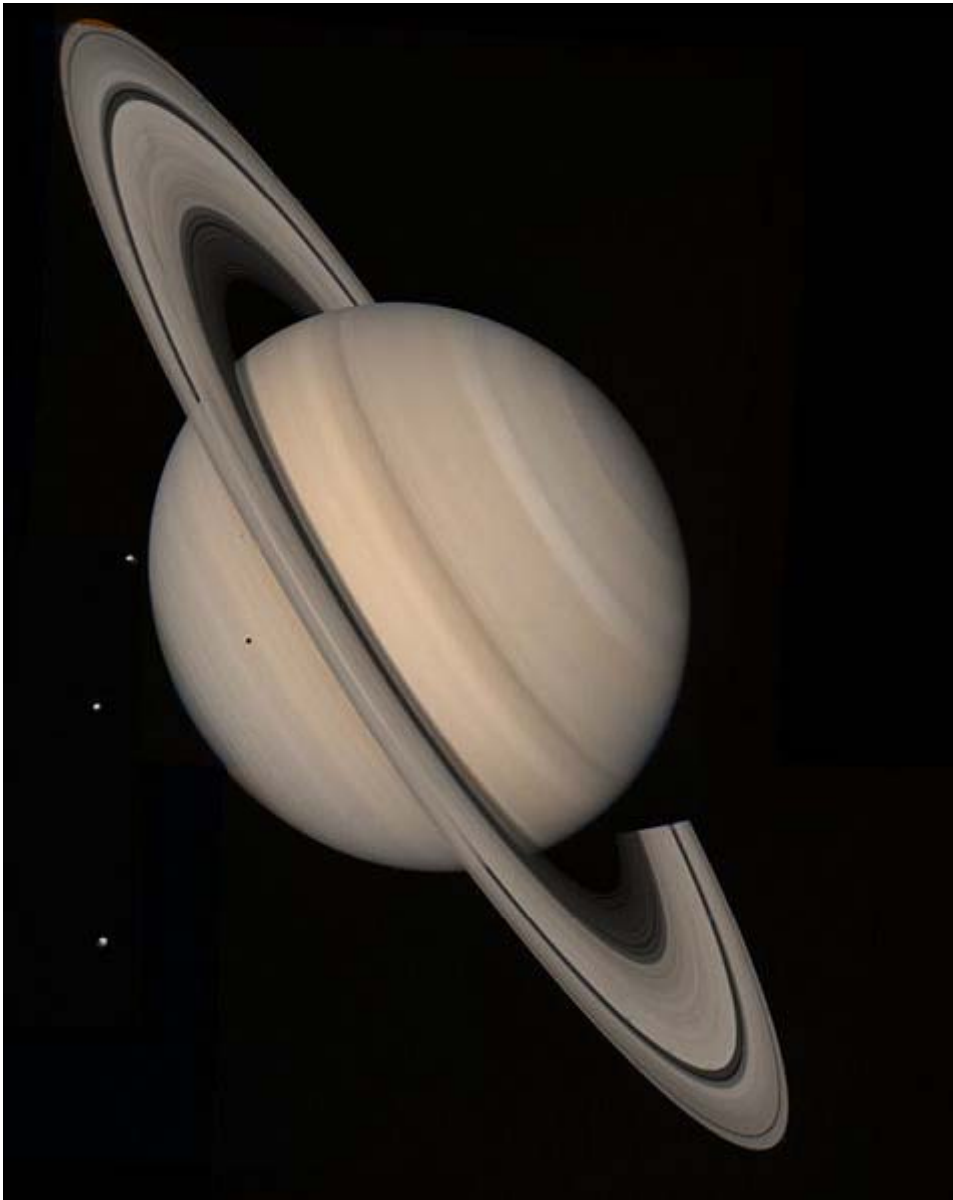
Bode's law

Average distance between planets
and the sun

sun-earth distance: 10

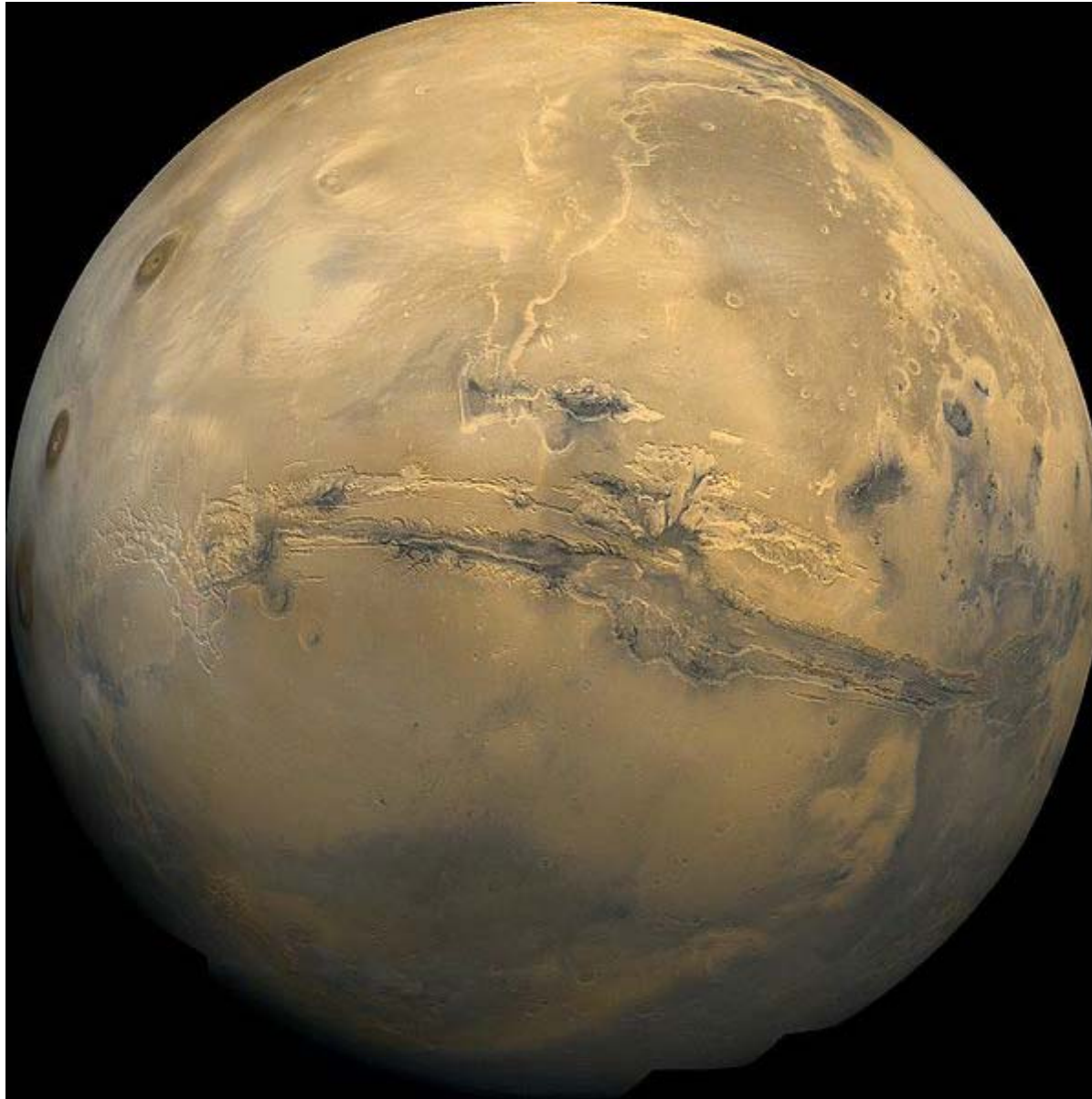
Mercury: 3.9 Venus: 7.2 Earth: 10
Mars: 15.2 Jupiter: 52 Saturn: 95.4





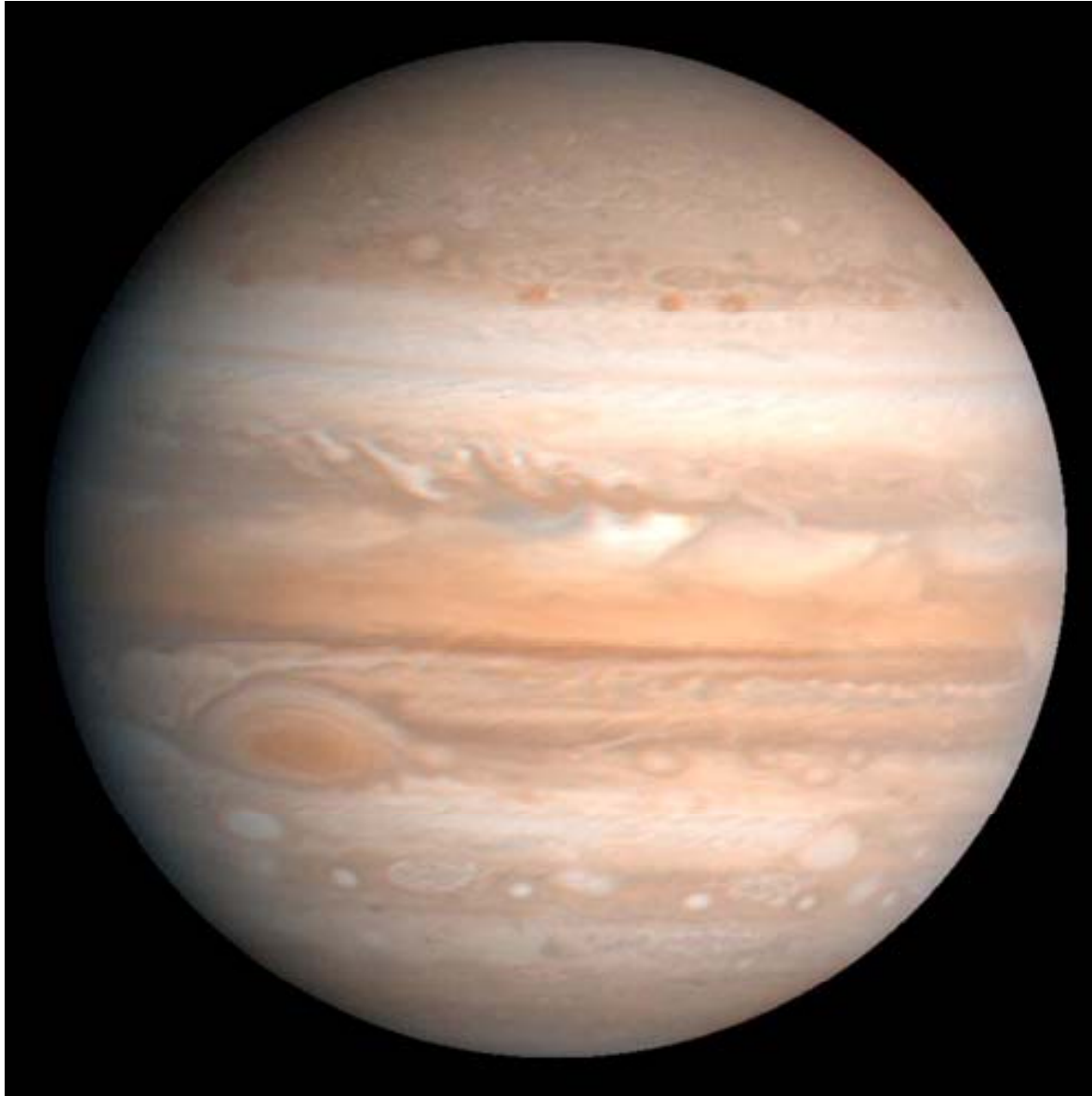
95.4





15.2





52



$$0 + 4 = 4,$$

$$3 + 4 = 7,$$

$$3 \times 2 + 4 = 10$$

$$3 \times 2^2 + 4 = 16,$$

$$3 \times 2^3 + 4 = 28,$$

$$3 \times 2^4 + 4 = 52,$$

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Mercury : 3.9

Venus : 7.2 Earth : 10

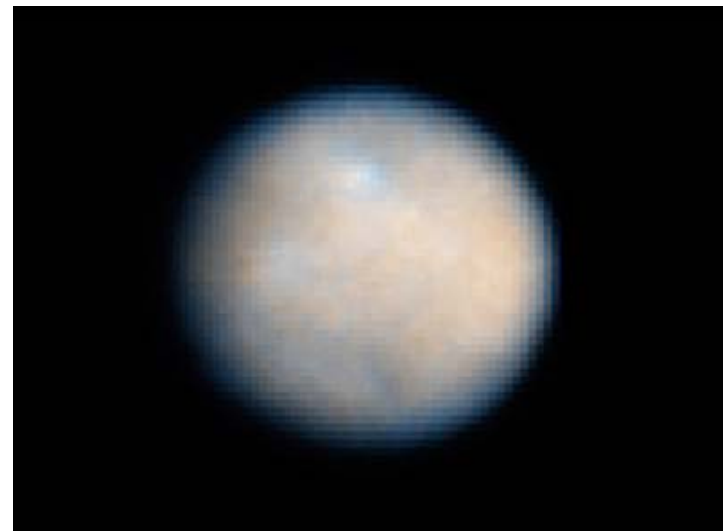
Mars : 15.2 Jupiter :

52 Saturn : 95.4



DISCOVERIES OF ASTEROIDS

- **28** is lacking!
- In **1801**, Asteroid Ceres(**27.7**) discovered
- And lost





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_Carl_Friedrich_Gauß,_1828.jpg](http://en.wikipedia.org/wiki/File:Bendixen_-_Carl_Friedrich_Gauß,_1828.jpg) (2010/03/02)

Carl Friedrich Gauss

1777-1855



CARL FRIEDRICH GAUSS, DIRECTOR OF GETTINGEN ASTRONOMICAL OBSERVATORY

- Orbital calculation and the
rediscovery of Ceres
- Least-square method adopted
- A new theory born



○ Global Focus on Knowledge

Creating Mathematics

-the Challenge of Mathematics-

(1st lecture) 2009-10-08

How mathematics was created

The mathematics for engineering and optimization

Kazuo Murota

Dept. of Mathematical Engineering and Information

Physics, Faculty of Engineering

Dept. of Mathematical Informatics, Graduate School of
Information Science and Technology

<http://www.misojiro.t.u-tokyo.ac.jp/~murota>



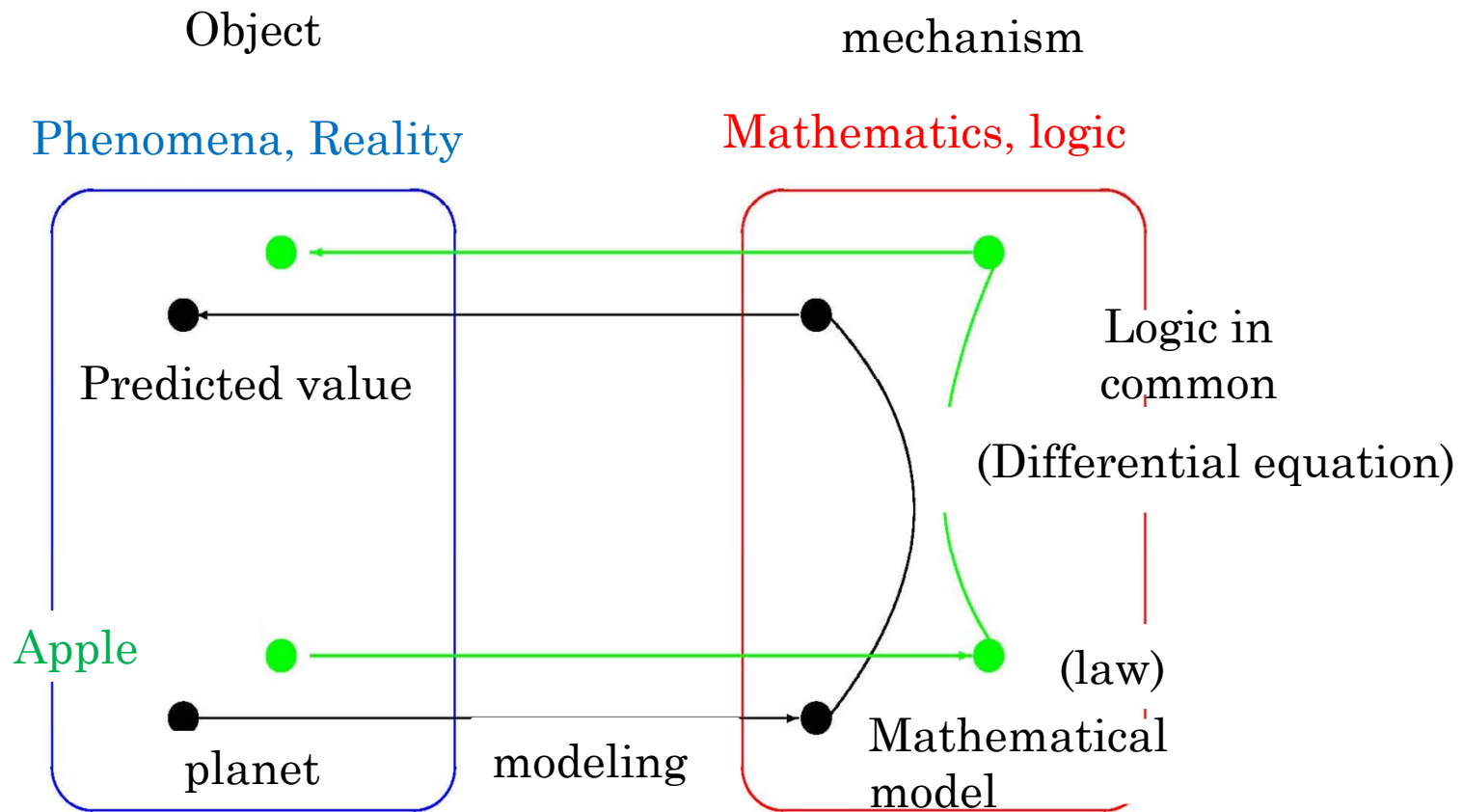
1. Mathematics in engineering

2. Mathematics in Optimization

3. Models and Data



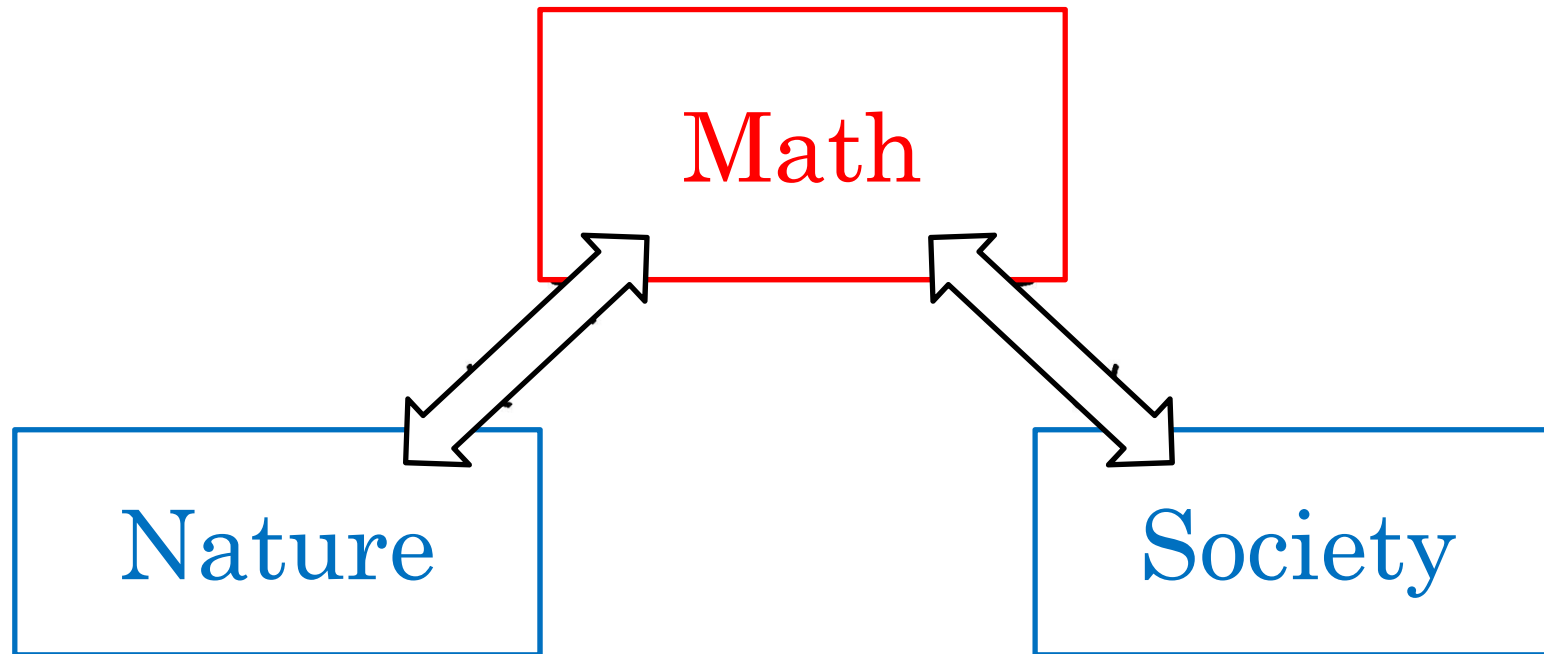
Phenomena and Mathematics

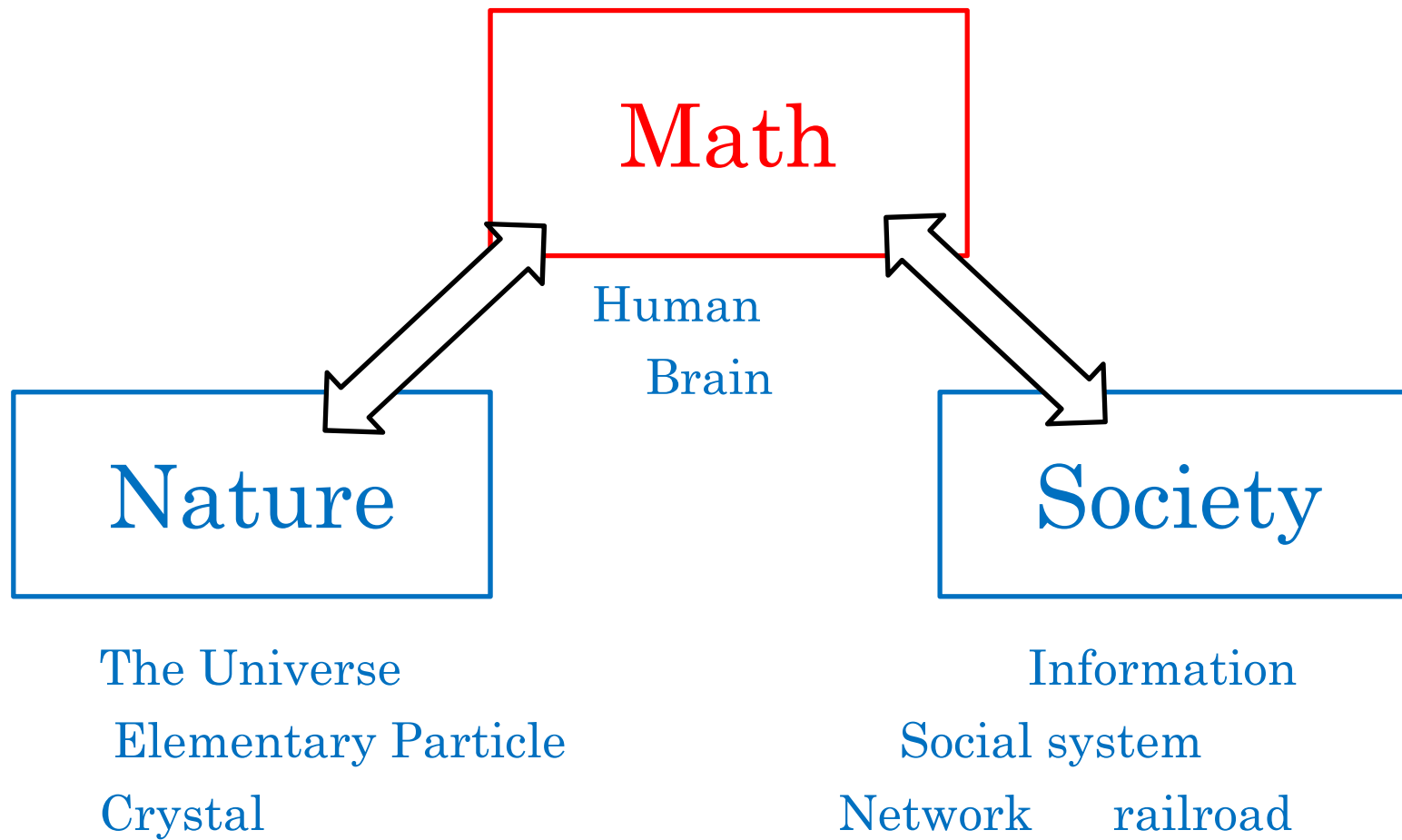


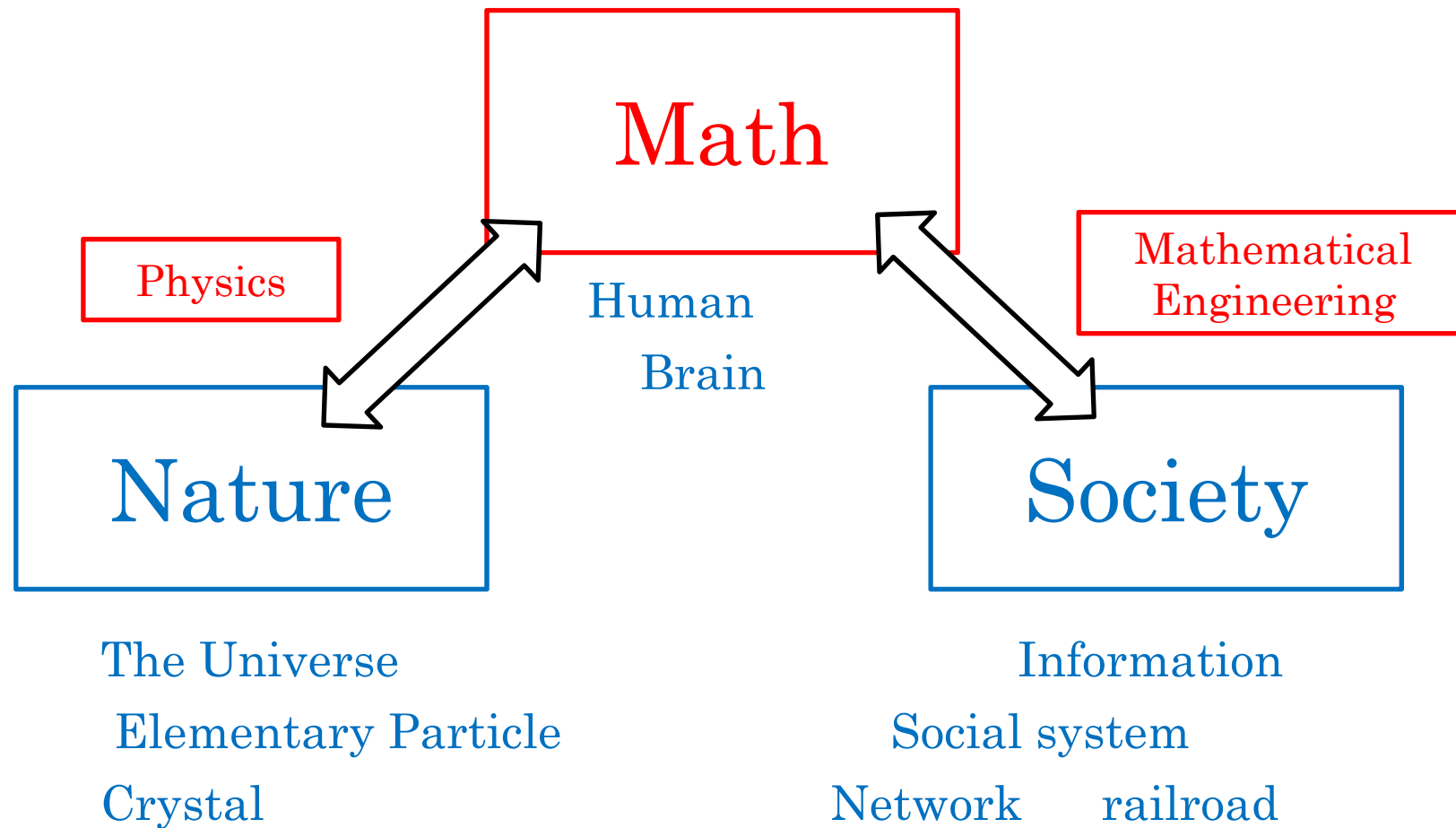
1. Mathematics in engineering



Driving force for mathematics







○ Mathematics for Engineering appears around 1945

Around 1800	celestial mechanics	Gauss
1900	Axiomatization of mathematics	Hilbert

Around 1945 Mathematics for engineering

2009 math, technology, and society today



Computation

- What is computation?
- Principles for Computers

Gödel, Turing

Neumann

⇒ Foundations of Mathematics, Computer Sciences,
Numerical Analysis



Computation

- What is computation? Gödel, Turing
 - Principles for Computers Neumann
- ⇒ Foundations of Mathematics, Computer Sciences,
Numerical Analysis

Information

- Quantitative treatment of Information Shannon
 - Cybernetics Wiener
- ⇒ Information Theory, Brain Science, Data Science



Computation

- What is computation? Gödel, Turing
 - Principles for Computers Neumann
- ⇒ Foundations of Mathematics, Computer Sciences,
Numerical Analysis

Information

- Quantitative treatment of Information Shannon
 - Cybernetics Wiener
- ⇒ Information Theory, Brain Science, Data Science

Planning/ Decision

- Linear Programming Dantzig
 - Game Theory von Neumann, Morgenstern
- ⇒ Optimization, Control Theory, Decision Making (OR)



Mathematics for Engineering: the Dawning

Around 1800	Celestial mechanics	Gauss
1900	Axiomatization of mathematics	Hilbert
Around 1930	the theory of Computation	Gödel, Turing
1944	Game Theory	von Neumann, Morgenstern
1945	Programmed computers	von Neumann
1947	Linear Programming	Dantzig
1948	Theory for Communication and Information	Shannon
1948	Cybernetics	Wiener



2. Mathematics for Optimization

Planning, Decision



○ Maximization / minimization problem

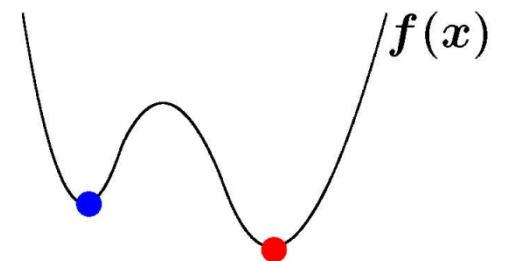
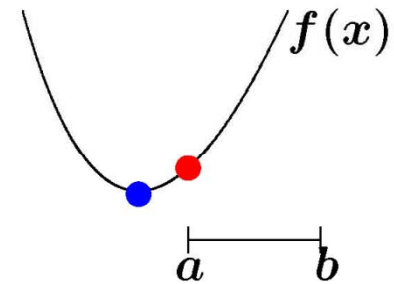
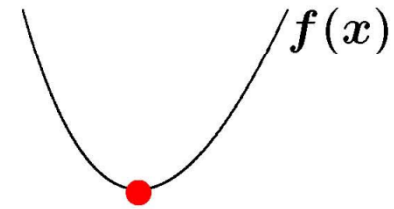
minimization $f(x)$

minimization $f(x) \Rightarrow f'(x) = 0$

Constraint condition $a \leq x \leq b$

Minimization $f(x_1, x_2, \dots)$

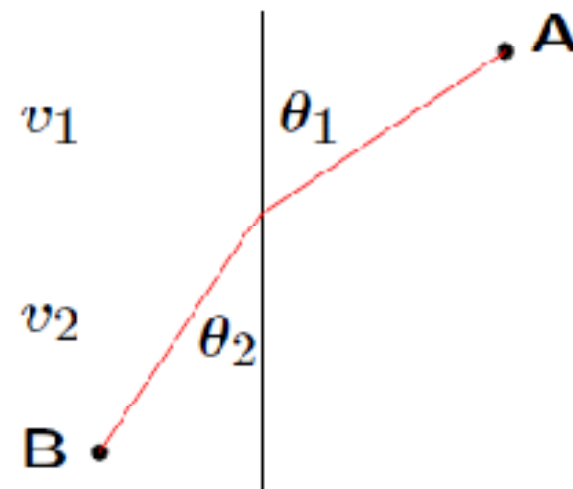
Constraint $(x_1, x_2, \dots) \in \mathbf{S}$



maximum minimum

Nature Chooses the Best— Variation Principle

Snell's Law: $\frac{\sin \theta_1}{\sin \theta_2} = \frac{v_1}{v_2}$



Fermat's Principle: the path taken between two points by a ray of light is the path that can be traversed in the least time

- least-action principle: motion path = minimization of action
- energy principle: equilibrium state = minimization of energy

Man Chooses the Best— Optimum Design



0 Series (1964)



300 Series (1992)



700 Series (1999)



By courtesy of Akio Sagawa, Railway Technical Research Institute

Mechanical design = optimization that enables ability ↑ cost

Mathematical expression (modeling)

⇒ calculation ⇒ experiment ⇒ manufacturing

- Man choose the optimum ...

Optimum Decision Making (Re)

- How to get to Hongo ㊦
from Komaba?
(13.7 km)

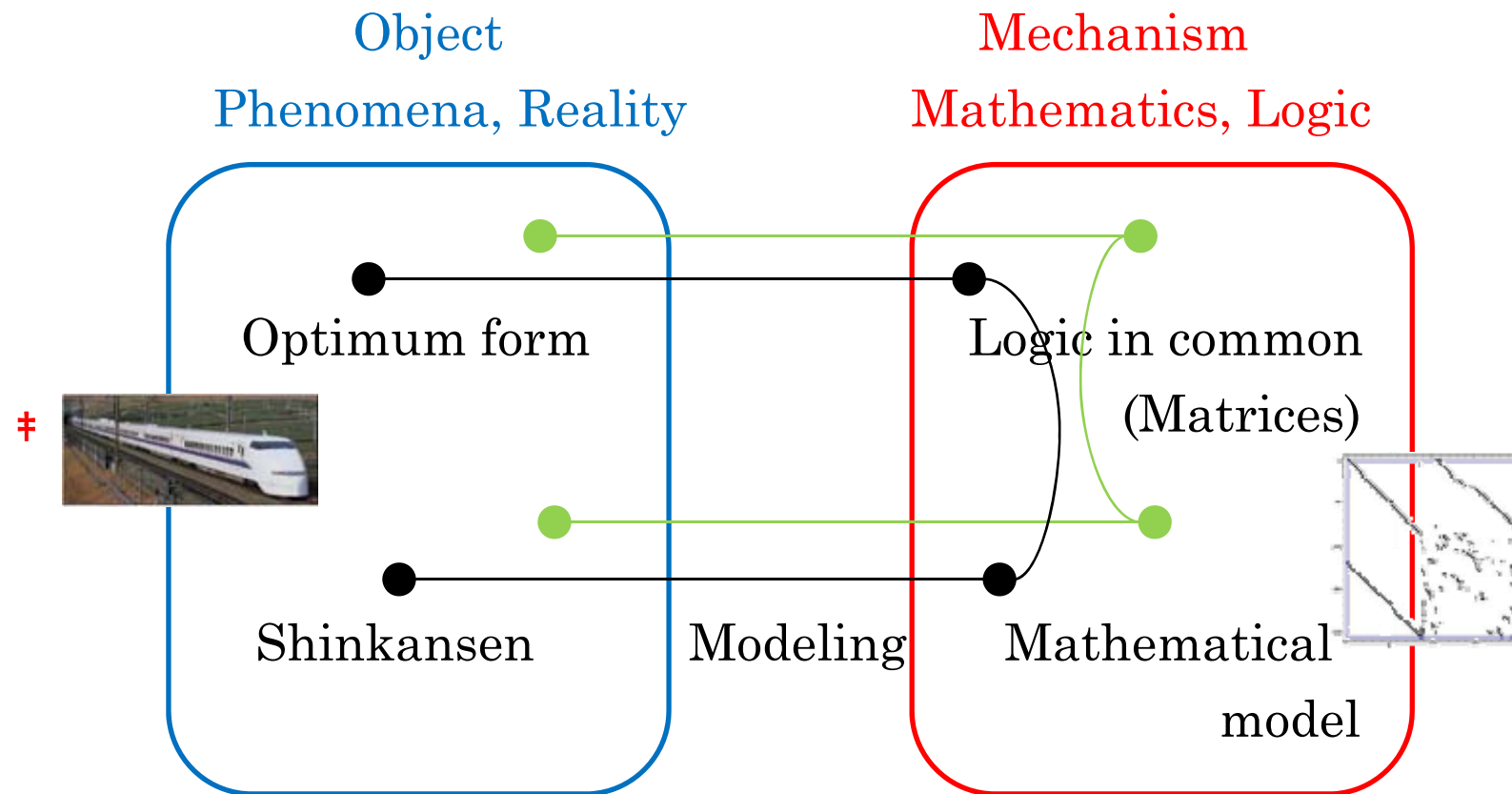


Goo map

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○ Phenomena and Mathematics



Matrices: common form

$n = ?$

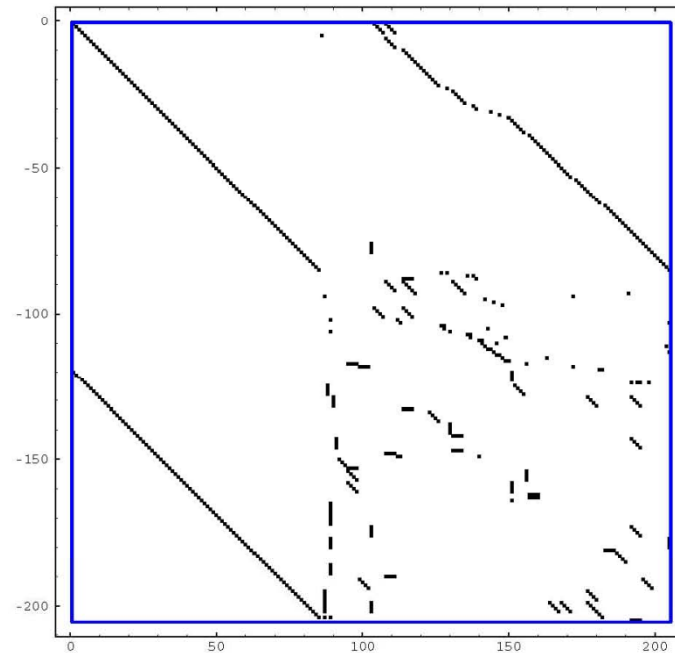
Math textbook

$$\begin{bmatrix} 2 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 3 & 2 \end{bmatrix}$$

White elements are all zero $\Rightarrow$

Large-scale, sparse matrix

Actual problem in Engineering



○ The World of Optimization

Operations Research

Mathematical programming

Modeling + Theory + Algorithm

Beautiful math

Useful math



○ Birth of Mathematical Programming

1947: Linear Programming

✦



G. Dantzig
(1914~2005)

✦



J. von Neumann
(1903~1957)

✦



L. V. Kantorovich
(1912~1986)

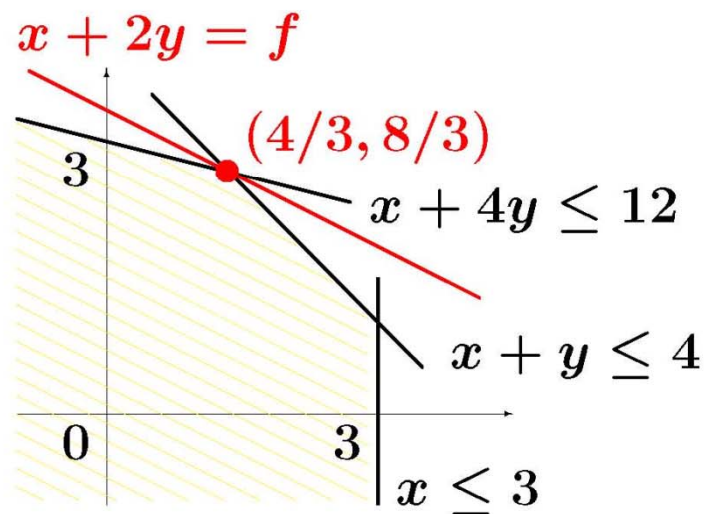
<http://www2.informs.org/Press/GeorgeDantzig.jpg>

<http://phil.elte.hu/redei/Utrecht/UtrechtNeumann.html>

<http://www.matematycy.interklasa.pl/images/matematycy/kantorovich.jpg>

- A Linear Programming problem in two variables

$$\begin{array}{ll}\text{Maximize} & x + 2y =: f \\ \text{subject to} & x + 4y \leq 12 \\ & x + y \leq 4 \\ & x \leq 3\end{array}$$



Solution: $(x, y) = \left(\frac{4}{3}, \frac{8}{3}\right)$

Value: $f = \frac{4}{3} + 2 \cdot \frac{8}{3} = \frac{20}{3}$

○ General form of Linear Programming Problems

Maximize $c^T x$
subject to $Ax \leq b$

Max. $x_1 + 2x_2$
s.t. $x_1 + 4x_2 \leq 12$
 $x_1 + x_2 \leq 4$
 $x_1 \leq 3$

Modeling: Linear Approximation is efficient for practical use

Theory: Duality Theorem

Algorithm: Simplex Method

Applications to Industrial society ↔ New aspects of Linear algebra

An example of “How Mathematics was Created”



○ Duality in Linear Programming Problems

-The meaning of transposed matrices

Primary Problem

$$\begin{array}{ll}\text{Max.} & c^T x \\ \text{s.t.} & Ax \leq b\end{array}$$

Dual Problem

$$\begin{array}{ll}\text{Min.} & b^T y \\ \text{s.t.} & A^T y = c \\ & y \geq 0\end{array}$$

$$\begin{array}{ll}\text{Max.} & x_1 + 2x_2 \\ \text{s.t.} & x_1 + 4x_2 \leq 12 \\ & x_1 + x_2 \leq 4 \\ & x_1 \leq 3\end{array}$$

$$\begin{array}{ll}\text{Min.} & 12y_1 + 4y_2 + 3y_3 \\ \text{s.t.} & y_1 + y_2 + y_3 = 1 \\ & 4y_1 + y_2 = 2 \\ & y_1, y_2, y_3 \geq 0\end{array}$$

Duality Theorem: Max. of Primary Problem = Min. of Dual Problem



○ Let us Solve a Dual problem

$$(u, v, w) = (y_1, y_2, y_3)$$

$$\begin{array}{ll} \text{Minimize} & 12u + 4v + 3w =: g \cdots (1) \\ \text{subject to} & u + v + w = 1 \cdots (2) \\ & 4u + v = 2 \cdots (3) \\ & u, v, w \geq 0 \cdots (4) \end{array}$$

$$(3) \rightarrow v = 2 - 4u \geq 0$$

$$(2) \rightarrow w = 1 - u - v = -1 + 3u \geq 0$$

$$(1) \rightarrow g = 12u + 4(2 - 4u) + 3(-1 + 3u) = \boxed{5 + 5u}$$

$$(4) \rightarrow \boxed{1/3 \leq u \leq 1/2}$$

Solution: $(u, v, w) = \left(\frac{1}{3}, \frac{2}{3}, 0\right)$ **Optimal Value:** $g = 5 + 5 \cdot \frac{1}{3} = \frac{20}{3}$

○ Let us Solve a Dual problem

$$(u, v, w) = (y_1, y_2, y_3)$$

$$\begin{array}{ll} \text{Minimize} & 12u + 4v + 3w =: g \cdots (1) \\ \text{subject to} & u + v + w = 1 \cdots (2) \\ & 4u + v = 2 \cdots (3) \\ & u, v, w \geq 0 \cdots (4) \end{array}$$

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Solution: $(u, v, w) = \left(\frac{1}{3}, \frac{2}{3}, 0\right)$ **Optimal Value:** $g = 5 + 5 \cdot \frac{1}{3} = \frac{20}{3}$

Max. of Primary Problem = $20/3$ = Min. of Dual Problem

Progress in Optimization theory (continuous variables)

1947	Linear Programming	Dantzig
1960	Nonlinear Programming, Newton method	Powell, Fletcher
1970	Convex analyses/ Duality Theory	Rockafellar
1979	Ellipsoid method	Khachiyan
1984	Interior Point Method	Karmarkar
1995	Semidefinite Programming	Alizadeh, Nesterov, Nemirovski

Theory: Linear/ Convex / Nonlinear

Environment: Increase in Computational Power



(reappear)

- Man choose the optimum ...

Optimum Decision Making

- How to get to Hongo
from Komaba?
(13.7 km)

≠



Goo map

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Mathematics for Engineering (Re)

Computation

- What is computation?
- Principles for Computers
- Computational Efficiency

Information

- Quantitative treatment of Information
- Cybernetics

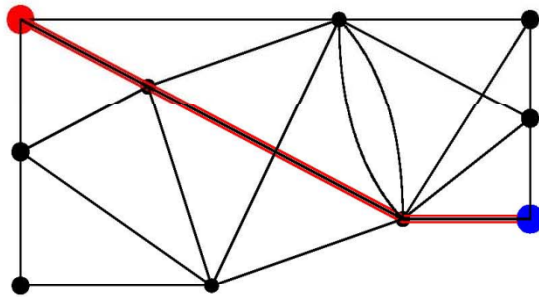
Planning/ Decision

- Linear Programming
- Game Theory



○ Discrete Optimization

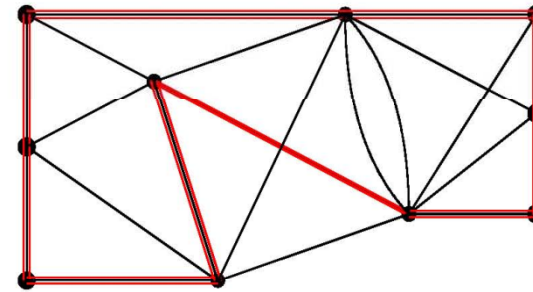
Continuous/Discrete



Shortest Path Problem

easy
P

(empirical fact)
(algorithmic theory)



Traveling Salesman Problem

very difficult
NP hard

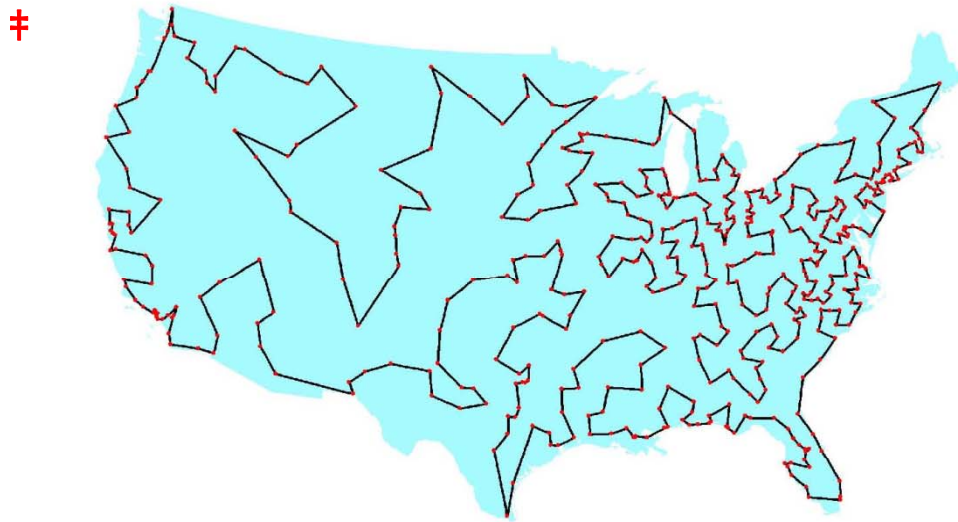
Shortest Path Problem

easy to solve

Traveling Salesman Problem

difficult to solve

⇒ demonstration (by Nobuyuki Tsuchimura)



532 cities, M. Padberg–G. Rinaldi (1987)

<http://www.tsp.gatech.edu/history/pictorial/att532.html>

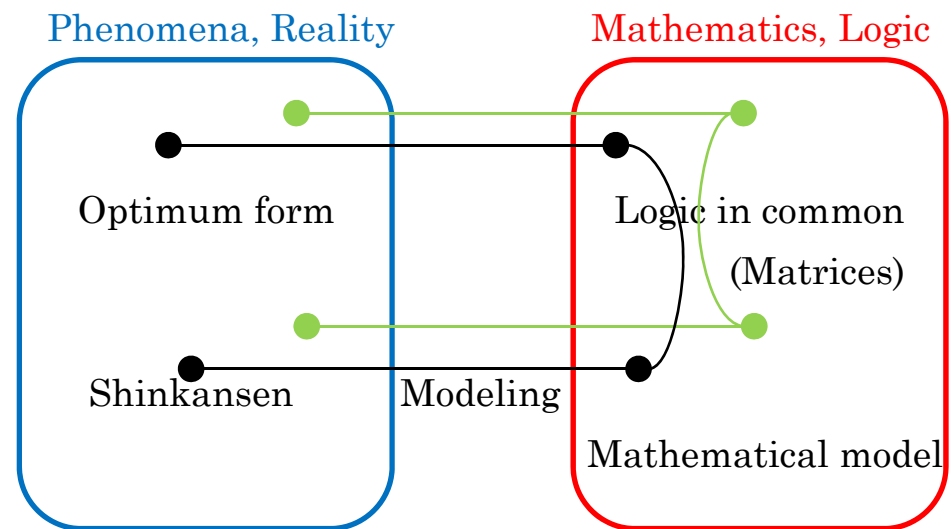


Progress in Discrete Optimization

1935	● Matroid	Whitney
1947	Linear programming (Simplex method)	Dantzig
1956	Flow network	Ford, Fulkerson
1960	Integer Programming (Cutting plane method)	Gomory
1970	● NP Complete	Cook, Levin
	● Graph algorithm	Tarjan
	Submodular Function	Edmonds
1980	Ellipsoid method	Khachiyan
1995	Approximation Algorithm	Goemans, Williamson
2000	Discrete Convex Analysis	Murota



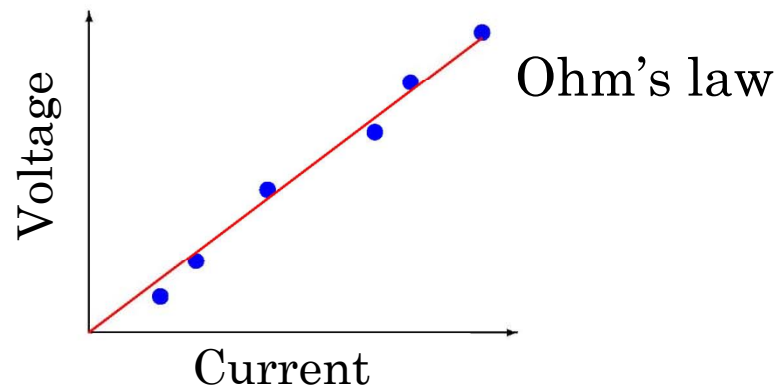
Models and Data



Models and Data

(Phenomenon $\Leftrightarrow$ Math)

$$V = RI$$

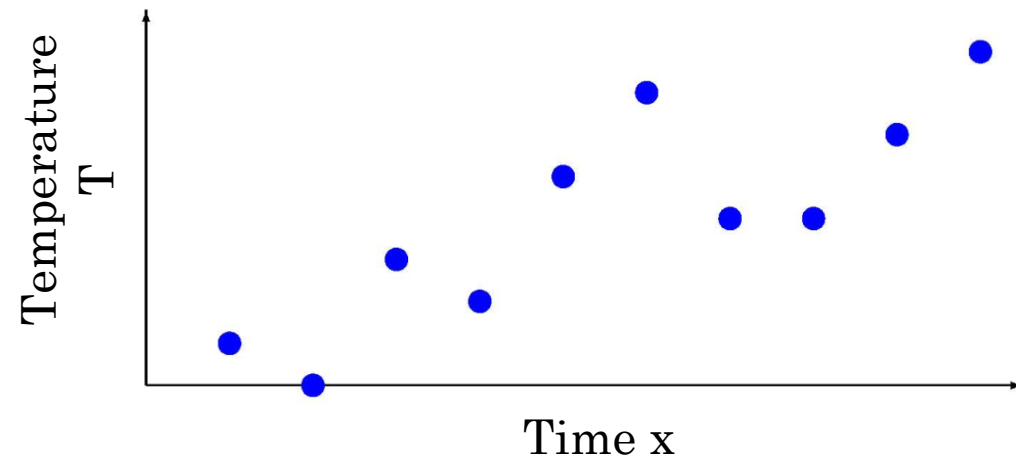


Collect **experimental data** and discover the **true model**

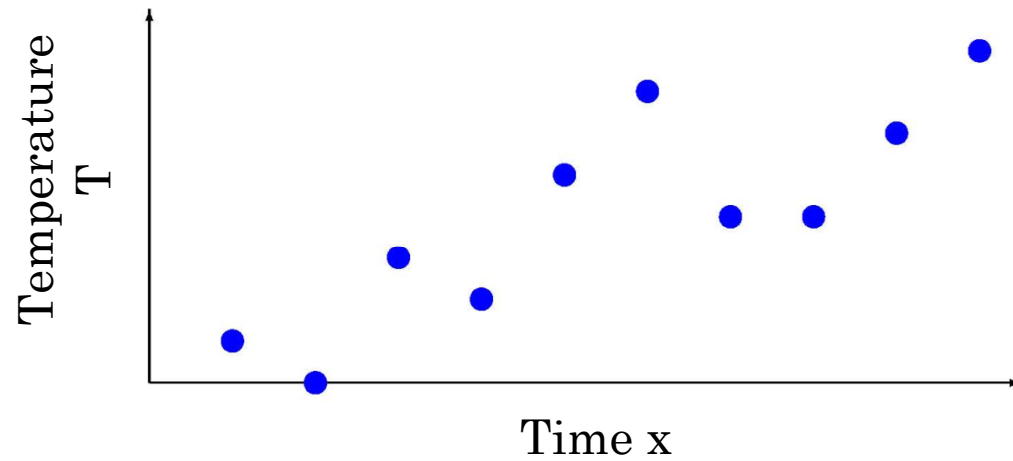
Least-square method (**Gauss**) :

$$f(R) = \sum_i (V_i - RI_i)^2 \rightarrow \min$$

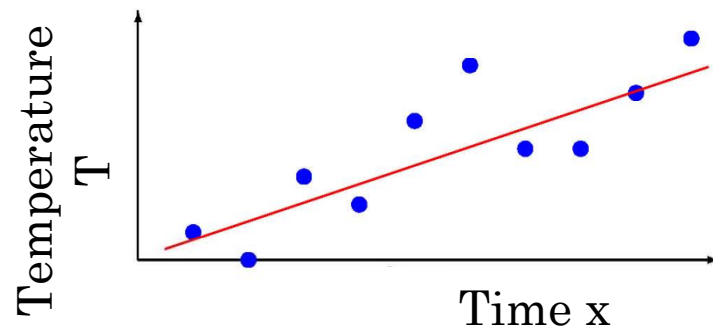

Model Fitting



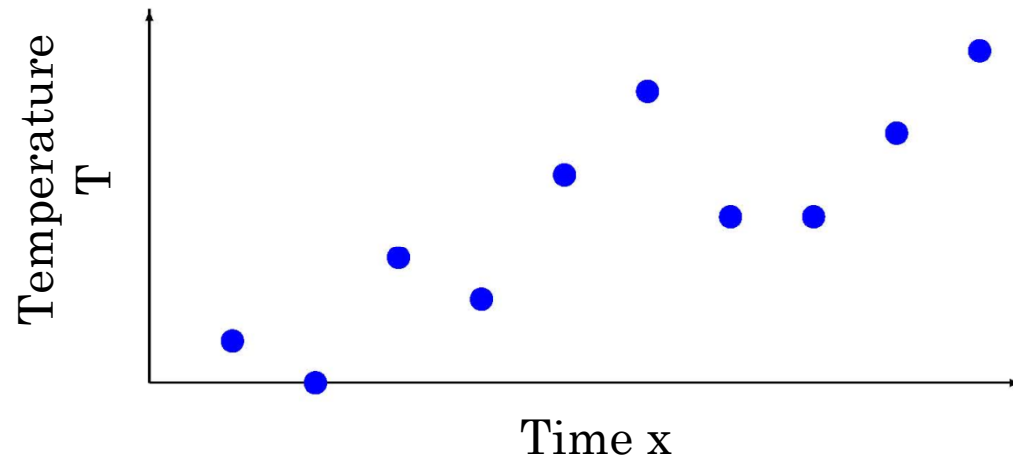
Model Fitting



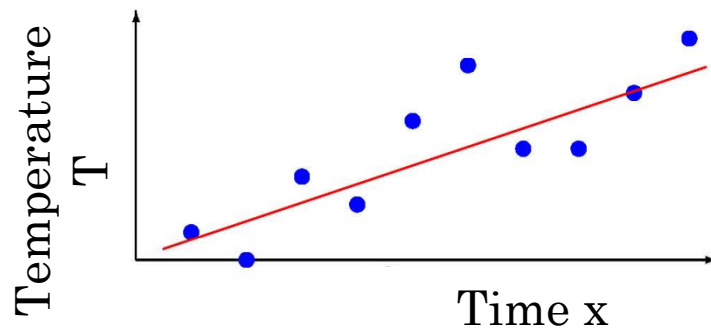
Linear function $T = ax + b$



Model Fitting

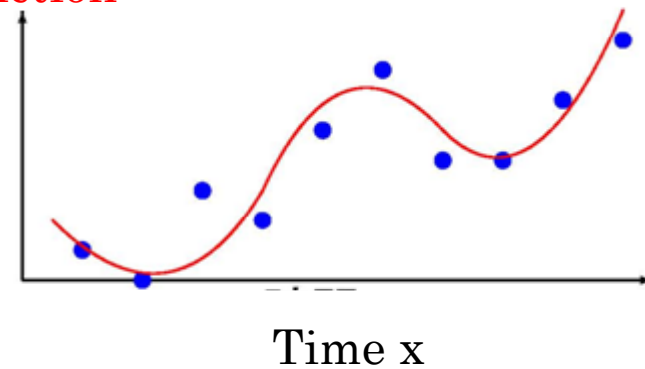


Linear function $T = ax + b$

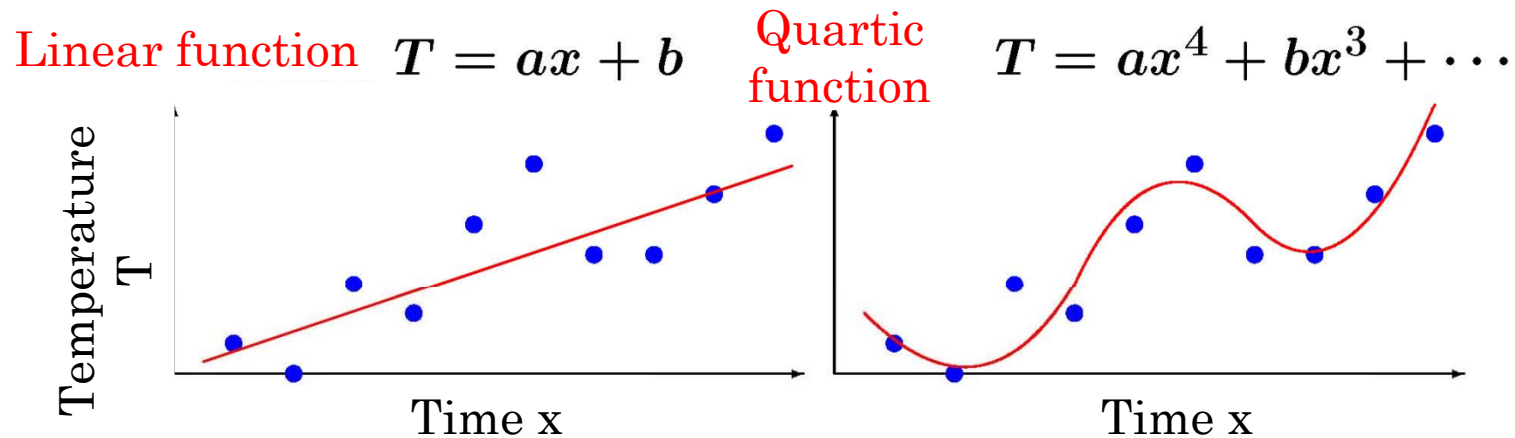


Quartic
function

$$T = ax^4 + bx^3 + \dots$$



What is a good model?



Complex Models are:

- Consistent with the data (explaining the past)
- Sensitive to errors, instable (predicting the future)

Consistency with the data

Simplicity of the model

Information Criterion

○ Akaike Information Criterion

(Consistency with the data)

(Simplicity of the model)

$$AIC = -2 (\log \text{likelihood}) + 2(\text{the number of parameters})$$

- 1974 Hirotugu Akaike (1927-2009)

⇒ Information Geometry
(Shun-ichi Amari)



○ The significance of mathematical model

Models are

- used to relate reality to mathematics
- not uniquely determined

Natural Sciences (Pure Science):

True Model the search for truth

Technological Sciences (Engineering):

Appropriate model means to achieve the purpose

⇒ modeling science



- Qualitative change of method for obtaining data

Past	Now (Web era)
make up by experiment / observation agricultural experiment Experimental planning (data gaining method) Analysis of variance (data analyzing method)	gather from around the world search engine (Yahoo!, Google) accumulative variance (information explosion) data mining

mathematical foundation: linear algebra (eigenvalue),
the concept of probability...



- Summary:

Mathematics <Mathematical Engineering> society

Math for technology

Computation

Information

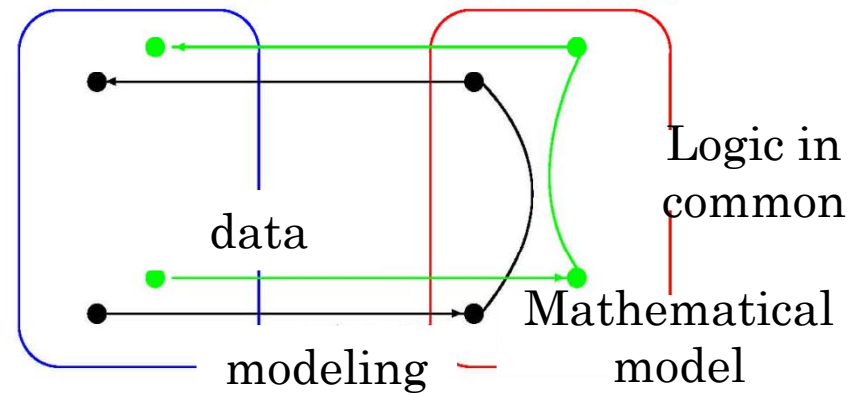
Planning, Decision

Mathematics for Optimization

Modeling + Theory + Algorithm

The meaning of mathematical models,

Qualitative change of data



Next lecture ...

